Shaft Type Ø18mm Incremental Rotary Encoder [NPN open collector/Voltage/No Amp. output]

Features

- Ultra-compact (Ø18mm) and ultra-lightweight (12g/10g)
- Easy installation in tight or limited spaces
- Low moment of inertia
- Power supply: 5VDC ±5%





[Axial cable type]

[Radial cable type]

CONTROLLERS

SENSORS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

Applications

/!

• Suitable for office machine such as ATMs, bill counting machines, copy machines



Ordering Information

E18S	2.5	- 200 -	- 1 -	- <u>N</u> -	- 5	- R	(C) LiDAR
Series	Shaft diameter	Pulses/revolution	Output phase	Control output	Power supply	Cable	(D) Door/Area
	2: Ø2mm 2.5: Ø2.5mm	100, 200, 300, 400	1: A	N: NPN open collector output V: Voltage output		R: Axial cable type S: Radial cable type	Door/Area Sensors
	2: Ø2mm 2.5: Ø2.5mm	200, 300	1: A	A: No Amp.	5: 5VDC ±5%	R: Axial cable type S: Radial cable type	(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets

Shaft Type Ø18mm Incremental Rotary Encoder [NPN open collector/Voltage output]

Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder		
Resolution (PPR) ^{*1}			100, 200, 300, 400		
ctrical specification	Output phase		A phase		
	Control output	NPN open collector output	Load current: max. 30mA, residual voltage: max. 0.4VDC		
		Voltage output	Load current: max. 10mA, residual voltage: max. 0.4VDC		
	Response time	output	Max. 1μs (cable length: 1m, I sink = 20mA)		
	(rise/fall)	Voltage output			
	Max. response frequency		25kHz		
	Power supply		5VDC== ±5% (ripple P-P: max. 5%)		
	Current consumption		Max. 50mA (disconnection of the load)		
	Insulation resistance		Over $100M\Omega$ (at 500VDC megger between all terminals and case)		
	Dielectric strength		500VAC 50/60Hz for 1 min (between all terminals and case)		
	Connection		Axial cable type, radial cable type		
on a	Starting torque		Max. 10gf·cm (9.8×10 ⁻⁴ N·m)		
Mechanical specification	Moment of inertia		Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)		
scifi	Shaft loadi	ng	Radial: max. 200gf, Thrust: max. 200gf		
₽ sq	Max. allowable revolution ^{**2}		6,000rpm		
Vibrat	ion		1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours		
Shock	Shock		Approx. max. 50G		
E		Ambient temperature	-10 to 70°C, storage: -20 to 80°C		
Environment		Ambient humidity	35 to 85%RH, storage: 35 to 90%RH		
Protection structure			IP50 (IEC standard)		
Cable			Ø1.28mm, 3-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø1.28mm)		
Accessory			Ø2mm coupling (supplied only for Ø2mm shaft diameter model)		
Approval					
Weight ^{#3}			Ø2mm Shaft diameter model: approx. 35.4g (approx. 12g) Ø2.5mm Shaft diameter model: approx. 34.2g (approx. 12g)		

%1: Not indicated resolutions are customizable.

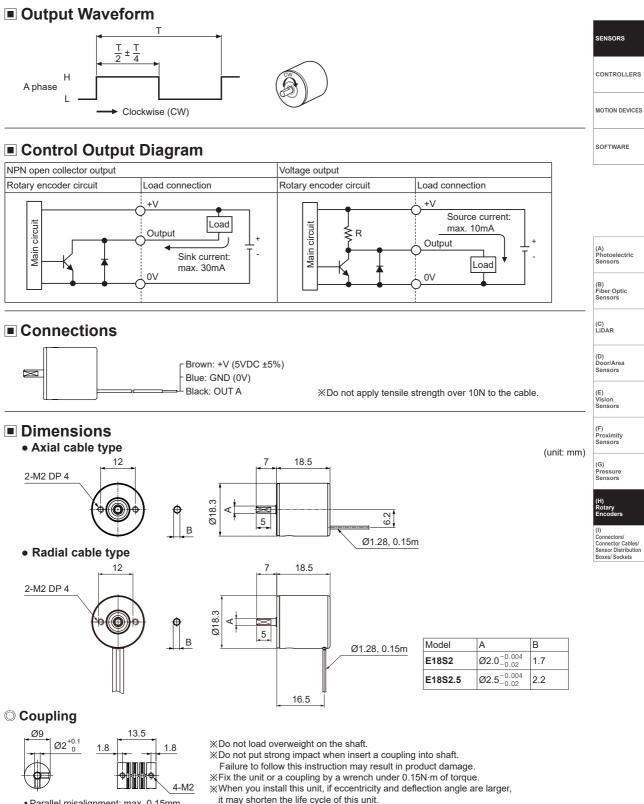
2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution (rpm)= <u>
Resolution</u> × 60 sec]

3: The weight includes packaging. The weight in parenthesis is for unit only.

*Environment resistance is rated at no freezing or condensation.

Incremental Ø18mm Shaft Type



Parallel misalignment: max. 0.15mm

Angular misalignment: max. 2

• End-play: max. 0.2mm

**For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.

※For flexible coupling (ERB series) information, refer to ERB series section



Shaft Type Ø18mm Incremental Rotary Encoder [No Amp. output]

Specifications

Item			Ø18mm shaft type of Incremental Rotary Encoder		
Resolution (PPR) ^{×1}			200, 300		
Electrical specification	Output phase		A phase		
	Output waveform		Quasi-sinusoidal (No Amp.)		
	Output signal amplitude		Min. 150mV _{P-P}		
	Output amplitude variation		Max. 40%		
	Max. response frequency		10kHz		
	Power supply		5VDC ±5% (ripple P-P: max. 5%)		
lect	Insulation resistance		Over $100M\Omega$ (at 500VDC megger between all terminals and case)		
Ш	Dielectric strength		500VAC 50/60Hz for 1 min (between all terminals and case)		
	Connection		Axial cable type, radial cable type		
		Current flow	I _F : max. 50mA		
lions	LED	Reverse voltage	V _R : max. 5VDC		
ficat		Current consumption	P _D : max. 95mW		
Optical elements specifications		Collector-Emitter voltage	V _{CEO} : max. 30VDC		
Op Its s	Photo	Emitter-Collector voltage	V _{ECO} : max. 5VDC		
mer	transistor	Collector current	I _c : max. 20mA		
e e		Collector Current consumption	P _c : max. 75mW		
n al	Starting torque		Max. 10gf·cm (9.8×10 ⁻⁴ N·m)		
anic catio	Moment of	inertia	Max. 0.5g·cm² (5×10 ⁻⁸ kg·m²)		
Mechanical specification	Shaft loading		Radial: max. 200gf, Thrust: max. 200gf		
	Max. allowable revolution ^{**2}		3,000rpm		
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each of X, Y, Z directions for 2 hours		
Shock			Approx. max. 50G		
Envir	onment	Ambient temperature	-10 to 70°C, storage: -20 to 80°C		
	Jiment	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH		
Protection structure			IP50 (IEC standard)		
Cable			Ø1mm, 4-wire, 150mm, Flat ribbon cable (AWG26, core diameter: 0.16mm, number of cores: 7, insulator diameter: Ø0.98mm)		
Accessory			Ø2mm coupling (only for the Ø2mm shaft diameter model)		
Weight ^{#3}			Approx. 33.5g (approx. 10g)		

 \times 1: Not indicated resolutions are customizable.

2: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution (rpm)= <u>Max. response frequency</u> × 60 sec]

3: The weight includes packaging. The weight in parenthesis is for unit only.

Environment resistance is rated at no freezing or condensation.

Incremental Ø18mm Shaft Type

Output Waveform SENSORS Sm Smir ※Output signal amplitude: S_{min}≥150mV_{P-P} CONTROLLERS Output amplitude variation: (S_{max}/S_{min}-1)×100≤40% MOTION DEVICES Control Output Diagram Internal circuit Measurement circuit SOFTWARE -0 +V O Collector Anode 1kΩ (black) (brown) -O Signal I_F=10mA ž Cathode ł Emitter С (blue) (white) (A) Photoelectric Sensors Encoder -0 0V (B) Fiber Optic Sensors Connections (C) LiDAR Brown: Anode Blue: Cathode \geq (D) Door/Area Black: Collector Sensors White: Emitter XDo not apply tensile strength over 10N to the cable. (E) Vision Sensors Dimensions (F) Proximity Sensors Axial cable type (unit: mm) 10 18.5 12 (G) Pressure Sensors 2-M2 DP 4 Ø18.3 (H) Rotary Encode O 6.2 6.6 В (1) Connectors/ Connector Cables/ Ø1, 0.15m Sensor Distribution Radial cable type Boxes/ Sockets 12 10 18.5 2-M2 DP 4 Ø18.3 0 ∢ 6.6 В Ø1, 0.15m Model Α В Ø2.0^{-0.01} 1.8⁰_{-0.1} E18S2 Ø2.5^{-0.01} 2.3_0 E18S2.5 16.5 ○ Coupling 13.5 Ø2^{+0.1} XDo not load overweight on the shaft. 1.8 1.8 *Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage. %Fix the unit or a coupling by a wrench under 0.15N m of torque. When you install this unit, if eccentricity and deflection angle are larger, 4-M2 it may shorten the life cycle of this unit. • Parallel misalignment: max. 0.15mm

• Angular misalignment: max. 2°

• End-play: max. 0.2mm

%For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.

%For flexible coupling (ERB series) information, refer to the ERB series section.

