## Autonics

## Portable handle type Rotary encoder(INCREMENTAL TYPE) **ENHP SERIES**

## INSTRUCTION MANUAL



Thank you for choosing our Autonics product Please read the following safety considerations before use.

## Safety Considerations

\*Please observe all safety considerations for safe and proper product operation to avoid hazards.

★▲ symbol represents caution due to special circumstances in which hazards may occur.

**★ Warning** Failure to follow these instructions may result in serious injury or death.

▲ Caution Failure to follow these instructions may result in personal injury or product damage.

## **⚠** Warning

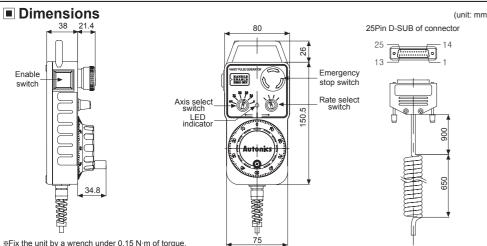
- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in fire, personal injury, or economic loss.
- 2. Install on a device panel to use.
- Failure to follow this instruction may result in fire.
- 3. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.
- 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire. 5. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire.

## **⚠** Caution

- 1. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage
- 2. Do not short the load.
- Failure to follow this instruction may result in product damage by fire.
- 3. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion.
- l. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

## Ordering Information

Model	Pulses/Revolution	Clickstopper position	Control output	Power supply
ENHP-100-1-T-5	-100 PPR	Normal "H"		5VDC±5%
ENHP-100-1-T-24			Totem pole output	12-24VDC±5%
ENHP-100-2-T-5		Normal "L"	Totern pole output	5VDC±5%
ENHP-100-2-T-24				12-24VDC±5%
ENHP-100-1-L-5		Normal "H"	Line driver output	5VDC±5%
ENHP-100-2-L-5		Normal "L"	Line driver output	
*Line driver power is only 5\	VDC.			



\*The above specifications are subject to change and some models may be discontinued without notice.

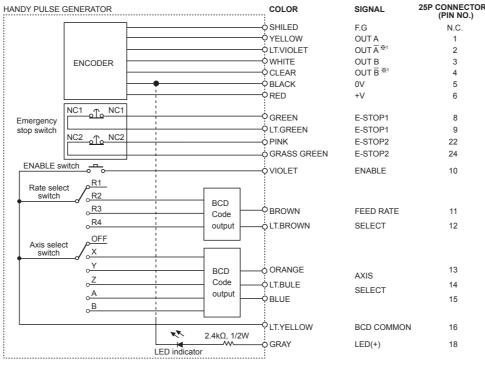
\*\*Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage)

## Specifications

Model		ENHP-100-1-T, ENHP-100-2-T	ENHP-100-1-L-5, ENHP-100-2-L-5	
Control output		Totem pole output	Line driver output	
Resolution (P	PR)	100		
Output phase		A, B phase	A, A, B, B phase	
	Phase difference of output	Phase difference between A and B : $\frac{1}{4} \pm \frac{1}{8}$ (T=1 cycle of A phase)		
	Rotary switch output	BCD Code output - AXIS SELECT SWITCH (OFF, X, Y, Z, A, B) - RATE SELECT SWITCH (R1, R2, R3, R4)		
Mechanical specification	Control output		[Low] - Load current : Max. 20mA,     Residual voltage : Max. 0.5VDC=      [High] - Load current : Max20mA,     Output voltage: Min. 2.5VDC=	
	Response time (Rise/Fall)	Max. 1 µs (Cable length: 1m, I sink=Max. 20mA)	Max. 0.5µs (Cable length: 1m, I sink=Max. 20maA	
	Power supply	●5VDC== ±5%(Ripple P-P: Max. 5%) ●12-24VDC== ±5%(Ripple P-P: Max. 5%)	5VDC ±5%(Ripple P-P: Max. 5%)	
	Current consumption	Max. 40mA(disconnection of the load)	Min. 50mA(disconnection of the load)	
	Max. Respose frequency	10kHz		
	Insulation resistance	Min.100MΩ (at 500VDC megger between all termi	nals and case)	
	Dielectric strength	750VAC 50/60Hz for 1 minute(Between all terminals and case)		
	Connection	25Pin D-SUB of connector type		
Mechanical specification	Starting torque	Max. 1kgf-cm (0.098N·m)		
	Shaft loading	Radial: 2kgf, Thrust: 1kgf		
	Max. allowable revolution *1	Max. 200rpm(Normal), 600rpm(Peak)		
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each X, Y, Z direction for 2 hours		
Shock		Max. 50G		
Environment	Ambient temperature	-10 to 70°C, storage: -25 to 85°C		
	Ambient humidity	35 to 85%RH, storage: 35 to 90%RH		
Protection structure <sup>*2</sup>		IP67(IEC standard) for Box		
Cable		Ø5mm, 18-wire, Length: 8m, Spring code cable (AWG28, Core wire diameter: Ø0.7mm)		
Unit weight		Approx. 730g		
W1. Make aure	that may reenenee re	avolution should be lower than or equal to may allow	undella recolution cuben colontina the recoultion	

- #1: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resoultion [Max. response revolution(rpm) =  $\frac{\text{Max. response frequency}}{\text{Max. response frequency}} \times 60 \text{ sec.}$ ]
- \*2: It is protection for the rear case and the wiring part.

#### Connections



#### AXIS SELECT

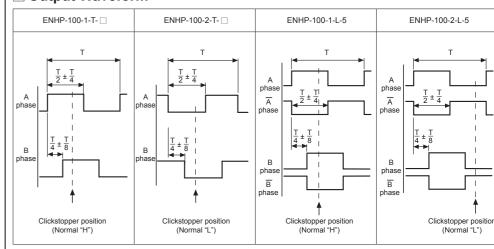
#### BCD Code output PIN NO 14 PIN NO 13 PIN NO 15 OFF X axis Y axis Z axis A axis B axis

#### ●RATE SELECT

-IUIT OLLLOI					
RATE	BCD Code output				
KAIE	PIN NO.12	PIN NO.11			
R1	0	0			
R2	0	1			
R3	1	0			
R4	1	1			

\*1: Totem pole output does not have A, B output signal. \*COMMON terminal (PIN NO.16) of Axis select switch and Rate select switch is common

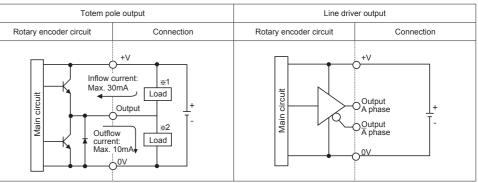
## Output Waveform



Clickstopper position Normal "H" or Normal "L": It shows the waveform when the handles is stopped



## Control Output Diagram



The output circuits of A. B phase (Line driver output A. A. B. B phase) are the same.

\*Totem pole output type can be used for NPN open collector output type (\*1) or voltage output type (\*2).

#### Cautions during Use

- 1. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
- 2. 5VDC, 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- 4. Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- 7. For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication
- 8. Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines.
- 9. This unit may be used in the following environments.
- ①Indoors (in the environment condition rated in 'Specifications')

Counters

■ Display Units

■ Temperature Controllers

■ Temperature/Humidity Transducer
■ SSRs/Power Controllers

■ Tachometer/Pulse (Rate) Meters

- ②Altitude max. 2.000m
- ③Pollution degree 2
- (4) Installation category II

### ■ Major Products

- Door Side Sensors
- Area Sensors
- Proximity Sensors
- Pressure Sensors ■ Rotary Encoders

- Connector/Sockets
   Switching Mode Power Supplies Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO₂, Nd: YAG)
   Laser Welding/Cutting System

# **Autonics** Corporation

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