

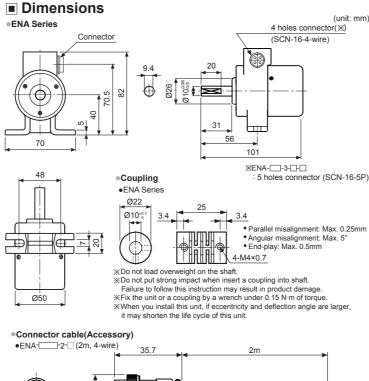
%The above specifications are subject to change and some models may be discontinued without notice %Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

## Specifications

| Item  |   | Side-mounting shaft type of incremental rotary encoder  | Wheel type of incremental rotary encoder   |  |  |  |
|---|---|---|--|--|--|--|
| Totem pole output                                     |   | ENA   | ENC-1  |  |  |  |
| NPN open  | collector output  | ENA-C   | ENC-1  |  |  |  |
| Voltage output  |   | ENAV  | ENC-1  |  |  |  |
| Resolution(PPR) <sup>×1</sup>                         |   | *1, *2, *5, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2048, 2500, 3000, 3600, 5000  | 1mm/Pulse, 1cm/Pulse, 1m/Pulse, 0.01yd/Pulse, 0.1yd/Pulse, 1yd/Pulse   |  |  |  |
| Output phase  |   | ENA   | A, B phase   |  |  |  |
|   |   | ENA   | A, b phase   |  |  |  |
| Phase difference of output                            |   | Output between A and B phase: $\frac{T}{4} \pm \frac{T}{8}$ (T= 1 cycle of A phase)   |  |  |  |  |
| Control   | Totem pole<br>output  | [Low] - Load current: Max. 30mA, Residual voltage: Max. 0.4VDC=<br>[High] - Load current: Max. 10mA, Output voltage(Power voltage 5VDC=): Min. (Power voltage-2.0)VDC=-,<br>Output voltage(Power voltage 12-24VDC=): Min. (Power voltage-3.0)VDC=   |  |  |  |  |
| output  | NPN open<br>collector output  | Load current: Max. 30mA, Residual voltage: Max. 0.4VDC==  |  |  |  |  |
|   | Voltage output  | Load current: Max. 10mA, Residual voltage: Max. 0.4VDC  |  |  |  |  |
| Response  | Totem pole<br>output  |   |  |  |  |  |
| time<br>(rise/fall)                                   | NPN open<br>collector output  | Max. 1µs (Cable length:2m, I sink = 20mA)   |  |  |  |  |
|   | Voltage output  |   |  |  |  |  |
| Max. Response frequency                               |   | 300kHz  | 180kHz   |  |  |  |
| Power supply  |   | •5VDC= ±5%(Ripple P-P: Max. 5%) •12-24VDC= ±5%(Ripple P-P: Max. 5%)   |  |  |  |  |
| Current consumption                                   |   | Max. 80mA(disconnection of the load)  |  |  |  |  |
| Insulation resistance                                 |   | Min. 100MΩ(at 500VDC megger between all terminals and case)   |  |  |  |  |
| Dielectric strength                                   |   | 750VAC 50/60Hz for 1 minute(Between all termials and case)  |  |  |  |  |
| Connection  |   | Radial connector type   | Axial cable type, Axial cable connector type   |  |  |  |
| Starting torque                                       |   | Max. 70gf·cm(0.007N·m)  | Dependent on the coefficient of friction   |  |  |  |
| Moment of inertia                                     |   | Max. 80g·cm <sup>2</sup> (8×10 <sup>-6</sup> kg·m <sup>2</sup> )  |  |  |  |  |
| Shaft loading   |   | Radial: 10kgf, Thrust: 2.5kgf   |  |  |  |  |
| Max. allowable revolution $^{\!\!\!\!\times\!\!\!^2}$ |   | 5000rpm   |  |  |  |  |
| Vibration   |   | 1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each X, Y, Z direction for 2 hours  |  |  |  |  |
| Shock   |   | Approx. Max. 75G  |  |  |  |  |
| Ambient temperature                                   |   | -10 to 70°C, Storage: -25 to 85°C   |  |  |  |  |
| Ambient humidity                                      |   | 35 to 85%RH, Storage: 35 to 90%RH   |  |  |  |  |
| ucture  |   | IP50(IEC Standards)   |  |  |  |  |
| Cable   |   | •ENA2   |  |  |  |  |
| Cable   |   | •ENA3   |  |  |  |  |
|   |   | Ø10mm coupling, Connector cable —   |  |  |  |  |
|   |   |   |  |  |  |  |
|   |   | CE  |  |  |  |  |
|   | NPN open -<br>Voltage out<br>PR) <sup>×1</sup><br>Phase diffe<br>Control<br>output<br>Response<br>time<br>(rise/fall)<br>Max. Resp<br>Power supp<br>Current cor<br>Insulation rn<br>Dielectric si<br>Connection<br>Starting tor<br>Moment of<br>Shaft loadir<br>Max. allowa | NPN open collector output           Voltage output           Voltage output           Phase difference of output           Control<br>output         Totem pole<br>output           Control<br>output         Totem pole<br>output           NPN open<br>collector output         NPN open<br>collector output           Response<br>time<br>(rise/fail)         Totem pole<br>output           NPN open<br>collector output         NPN open<br>collector output           Voltage output         NPN open<br>collector output           Max. Response frequency<br>Power supply         Current consumption<br>Insulation resistance<br>Dielectric strength<br>Connection           Starting torque         Moment of inertia           Shaft loading         Max. allowable revolution <sup>1/2</sup> Ambient temperature<br>Ambient humidity         Ambient humidity | Totem pole output         ENA-□-□-T-□           NPN open collector output         ENA-□-□-N-□           Voltage output         ENA-□-□-N-□           Y1-2: 45, 10, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1500, 1800, 2000, 2008, 2500, 3000, 3600, 5000           PR)*1         Y1-2: 45, 01, 12, 15, 20, 23, 25, 30, 35, 40, 45, 50, 60, 75, 100, 120, 125, 150, 192, 200, 240, 250, 256, 300, 360, 5000           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Control         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Phase difference of output         Output between A and B phase: 1/4 ± 1/8 (T= 1cycle of A phase)           Voltage output         Load current: Max. 30mA, Residual voltage: Max. 0.4VDC=::           Control         NPN open collector output           Voltage output         Load current: Max. 10mA, Residual voltage: Max. 0.4VDC=::           Woltage output         Max. 1µs (Cable length:2m, I sink = 20mA)           Voltage output         Max. 1µs (Cable length:2m, I sink = 20mA)           Gurrent consumption         Max. 800 Addisconnection of the load)           Insulation resistance         Min. 100MQ(at 500VDC megger between all terminals and case) <t< td=""></t<> |  |  |  |

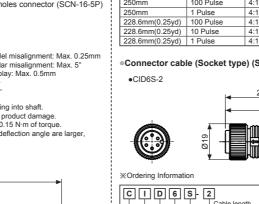
%2: Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution

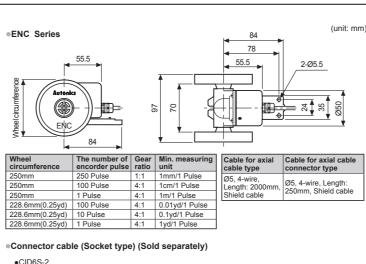
[Max. response revolution(rpm) = <u>Max. response frequency</u> × 60 sec]



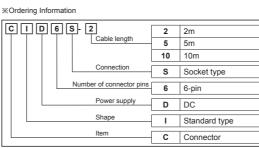
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35.7





2m (5m,10m) 43 Ø6























# Connections





-Black: OUT A White: OUT B -Orange: OUT Z -Brown: +V(5VDC, 12-24VDC ±5%) -Blue: GND(0V) Shield: F.G

- \*Unused wires must be insulated.
  \*The metal case and shield cable of encoder should
- be arounded(F.G.). \*Do not apply tensile strength over 30N to the cable.

### ENC Series

#### Axial cable type

- Black: OUT A - White: OUT B - Orange: N.C.(Not connected) - Brown: +V(5VDC, 12-24VDC ±5%) Blue: GND(0V)

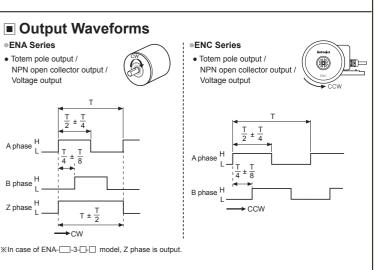
- \*Unused wires must be insulated
- %The metal case and shield cable of encoder should be grounded(F.G.).
- %Do not apply tensile strength over 30N to the cable

|            | Pin No. | Cable color | Function |
|------------|---------|-------------|----------|
|            | 1       | Black       | OUT A    |
| ((3 2))    | 2       | White       | OUT B    |
|            | 3       | Brown       | +V       |
|            | 4       | Blue        | GND      |
| (          | 1       | Black       | OUT A    |
|            | 2       | White       | OUT B    |
| (( ) ( )   | 3       | Orange      | OUT Z    |
|            | 4       | Brown       | +V       |
| $\bigcirc$ | 5       | Blue        | GND      |

#### Axial cable connector type

| Pin No. | Cable<br>color | Function |
|---------|----------------|----------|
| <br>1   | Black          | OUTA     |
| <br>2   | White          | OUT B    |
| 3       | Orange         | N.C.     |
| 4       | Brown          | +V       |
| <br>5   | Blue           | GND      |
| 6       | Shield         | F.G.     |

%F.G.(Field Ground) : It should be grounded separately



### Caution during Use

1. Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.

- 2. 5VDC, 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- 3. For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- . Ground the shield wire to the F.G. terminal.
- 5. When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- 6. Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- . Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines. 8. This unit may be used in the following environments.
- (Indoors (in the environment condition rated in 'Specifications')

SSRs/Power Controllers

Tachometer/Pulse (Rate) Meters

Counters

Panel Meters

Timers

- ②Altitude max. 2,000m
- ③Pollution degree 2
- ④Installation category II

# Major Products

- Photoelectric Sensors Temperature Controllers Fiber Optic Sensors
- Temperature/Humidity Transducers Door Sensors
- Door Side Sensors
- Area Sensors
- Proximity Sensors
- Pressure Sensors
- Rotary Encoders Display Units
- Connector/Sockets Sensor Controllers
- Switching Mode Power Supplies
- Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, CO<sub>2</sub>, Nd: YAG) Laser Welding/Cutting System

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